

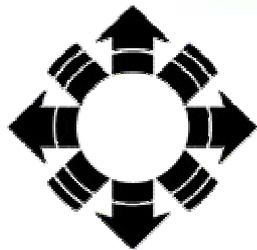
# HEV Control Strategy for Real-Time Optimization of Fuel Economy and Emissions

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**NREL**

**National Renewable Energy Laboratory**





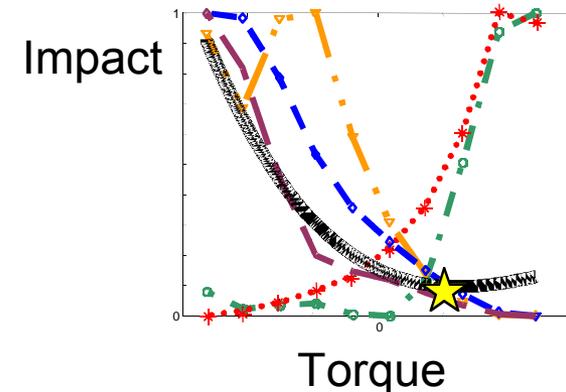
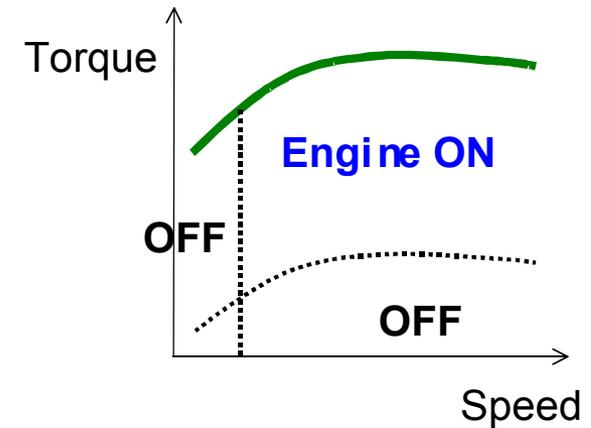
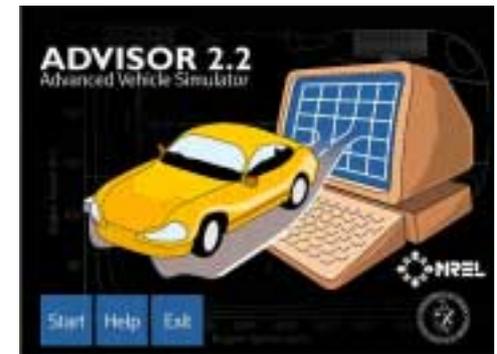
# Outline

- Motivation and Introduction
- Guiding Concepts in Real-Time Control Strategy (RTCS)
- RTCS Concepts Explained
- Simulation Results
- Summary of RTCS
- Conclusions and Future Work



# Motivation

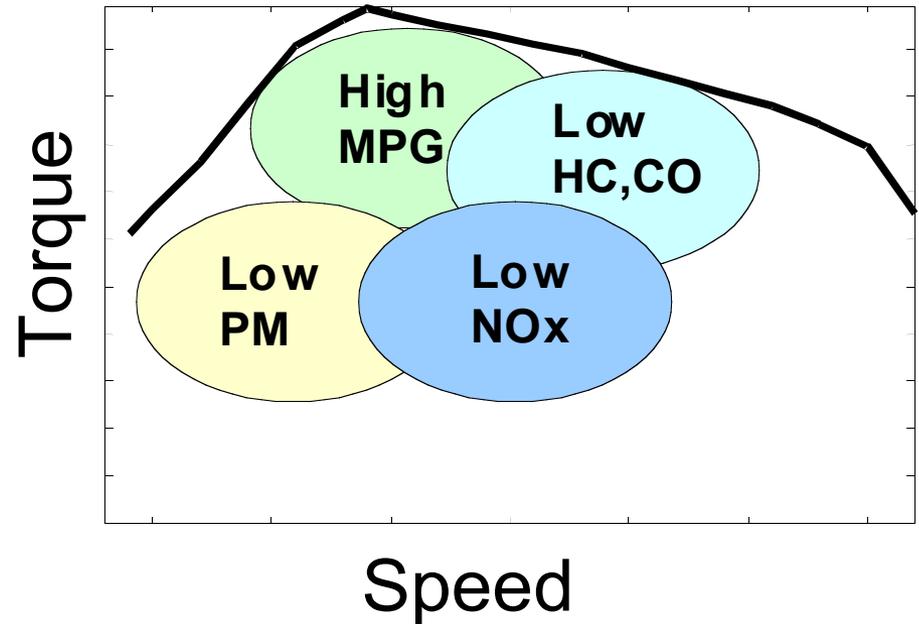
- Background: Parallel control strategies focus on **energy use**
  - Electric assist, motor used:
    - startup
    - low speeds, low torques
    - additional torque
  - Prius, Insight
- Goal of RTCS: Consider both **fuel economy** and **emissions**





# Introduction

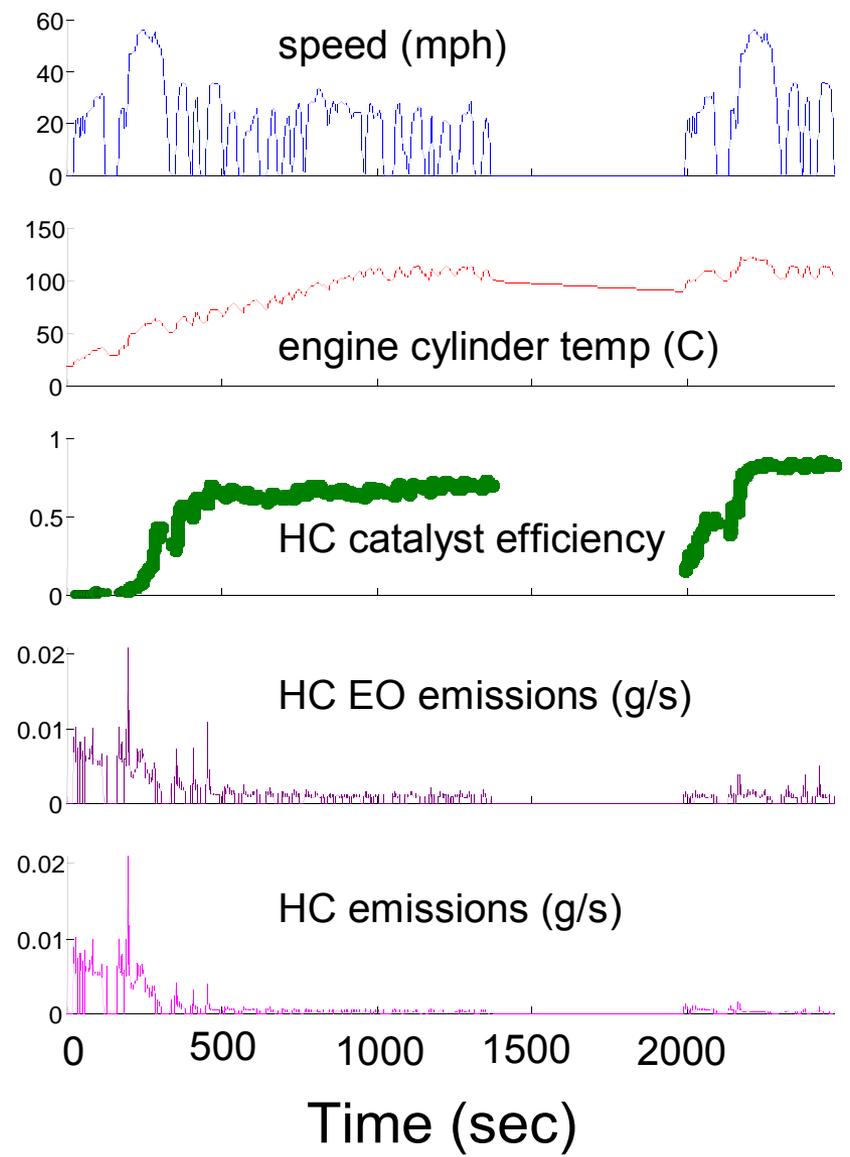
- **Tradeoffs** exist between optimum operating points for ICE fuel efficiency & emissions
- Must account for the energy used by the **electric side** of the hybrid





# Introduction

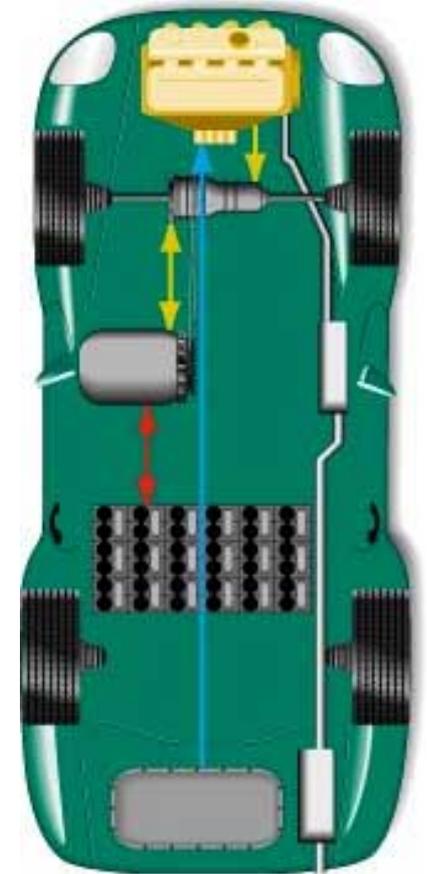
- Emissions and fuel use vary with temperature of engine, catalyst
  - 25-55% emissions when  $T_{\text{engine}} < 95^{\circ}\text{C}$
- RTCS can shift emphasis
  - cold->emissions
  - hot->fuel economy





# Guiding Concepts in Real Time Control Strategy (RTCS)

- **Entire vehicle** optimization
  - Includes instantaneous efficiencies of engine, exhaust removal, motor, and batteries
- **Real Time** Optimization of operating points
  - Includes temperature effects
- Amount of **free regenerative energy** calculated as the vehicle drives
  - Smoothing window in time





# Guiding Concepts in RTCS, cont.

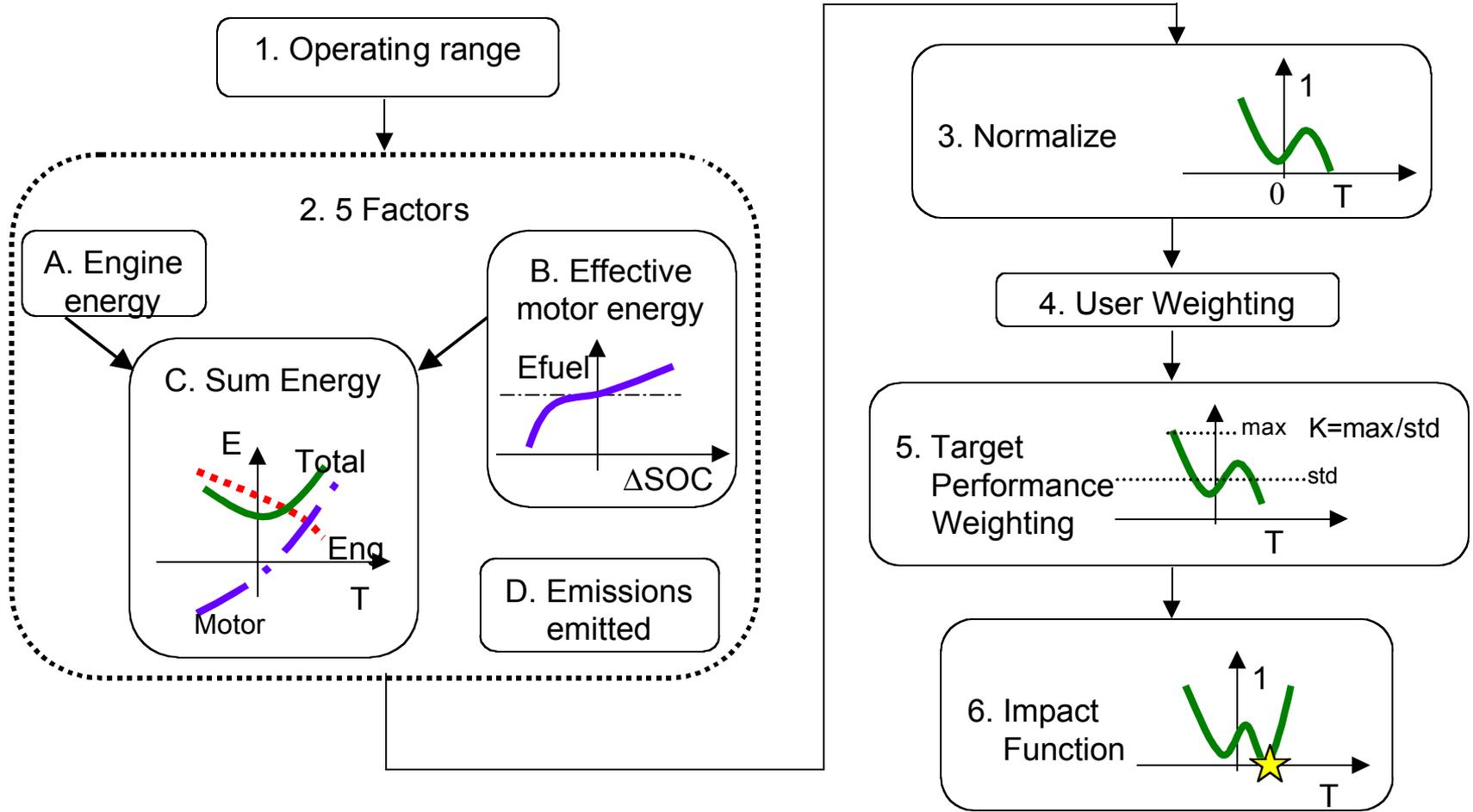
- **User-definable** targets for fuel economy and emissions
- **Entire range** of possible motor-engine torque combinations used
  - Optimums determined at each second
- Performance is weighted sum of instantaneous mpg and g/mi by **minimizing Impact Function**

Metric	Value	Unit
<i>Energy</i>	80	mpgge
<i>HC</i>	0.125	grams/mile
<i>CO</i>	1.7	grams/mile
<i>NOx</i>	0.07	grams/mile
<i>PM</i>	0.08	grams/mile

Based on PNGV goals and Tier 2 levels proposed (see [www.epa.gov/oms/tr2home](http://www.epa.gov/oms/tr2home))



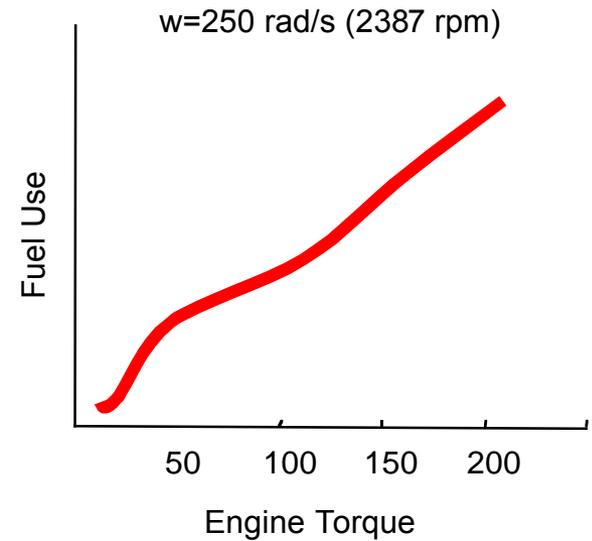
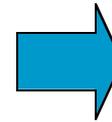
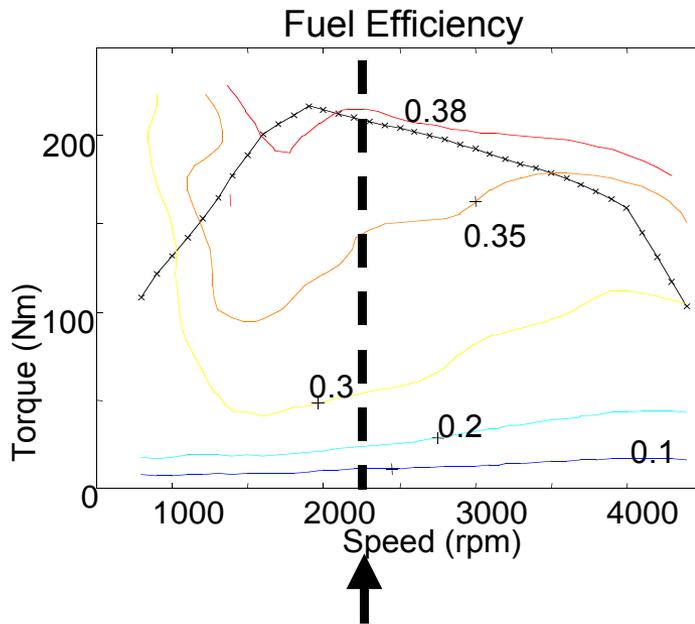
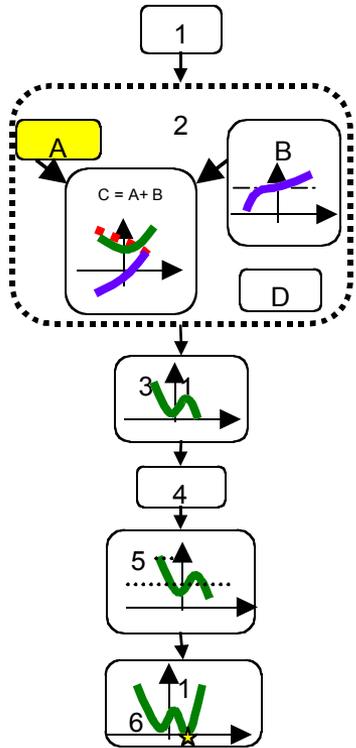
# RTCS Flow Chart



Real Time Control Strategy



# Fuel Energy vs. Torque

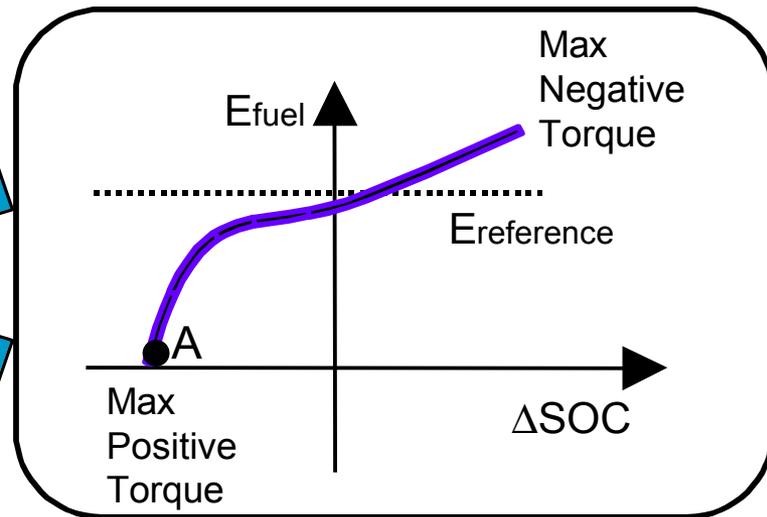
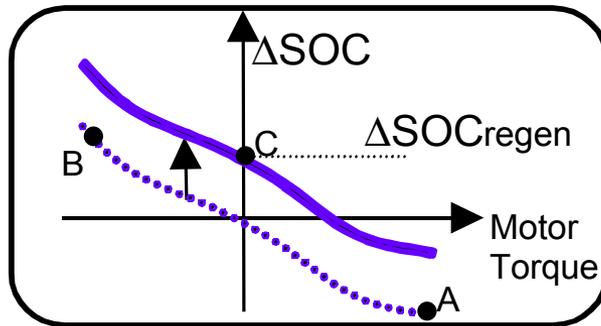
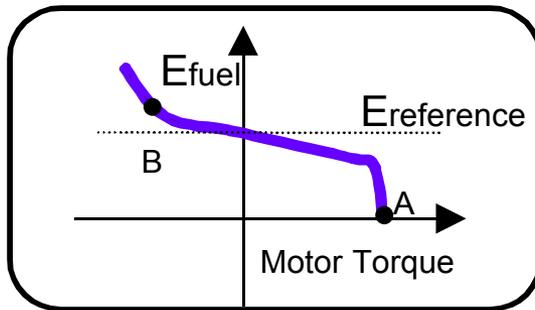
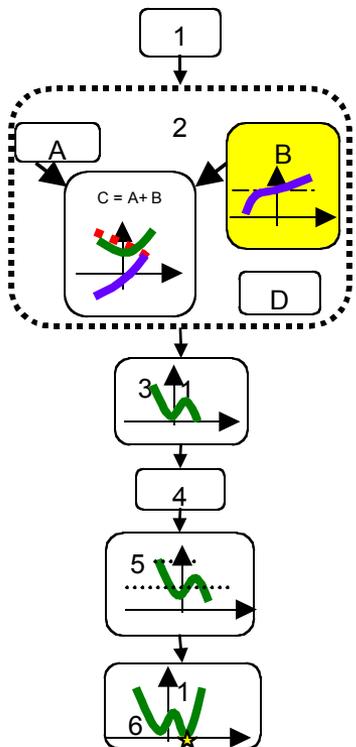


Real Time Control Strategy



# Effective Motor/Battery Energy

- Battery energy used is converted to an equivalent fuel
  - “Replacement-Energy” assuming similar operating conditions in the future

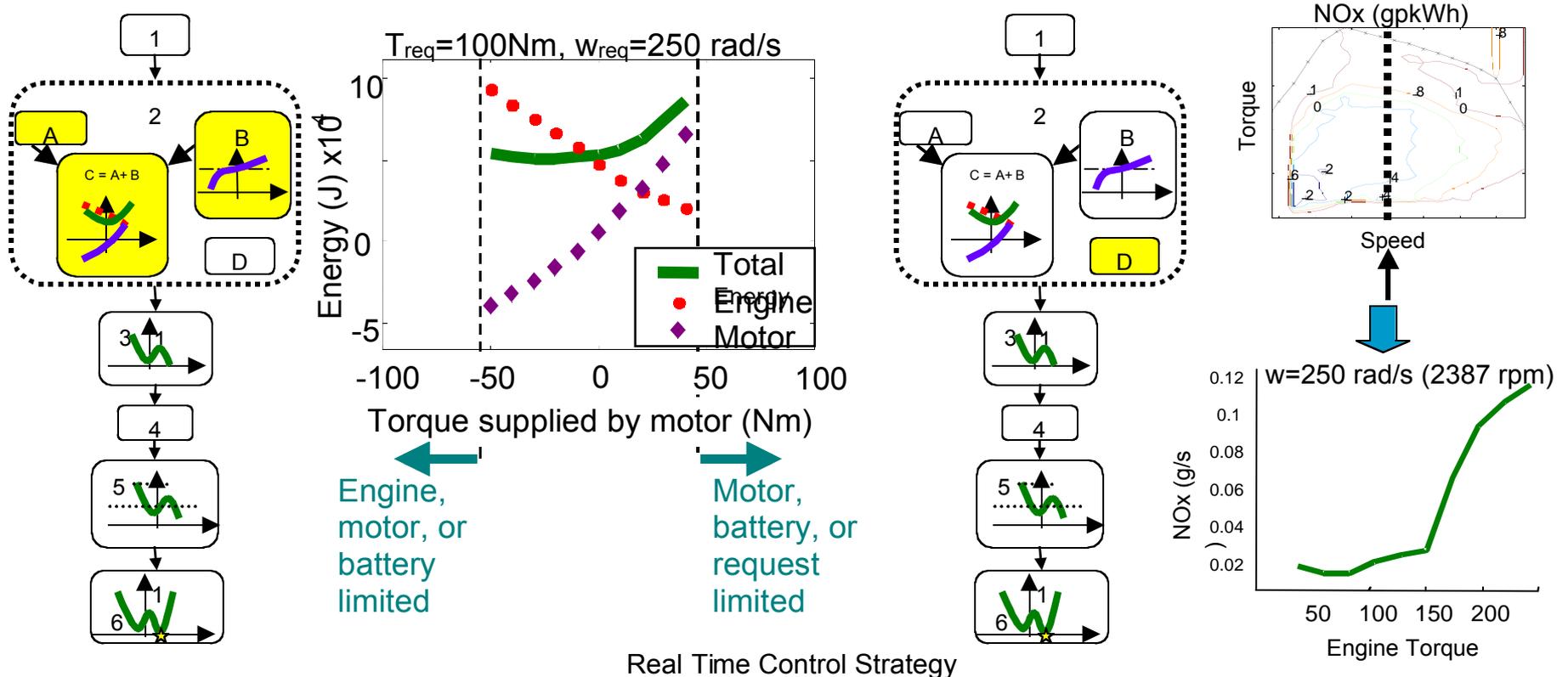


Real Time Control Strategy



# Energy & Emissions vs. Torque

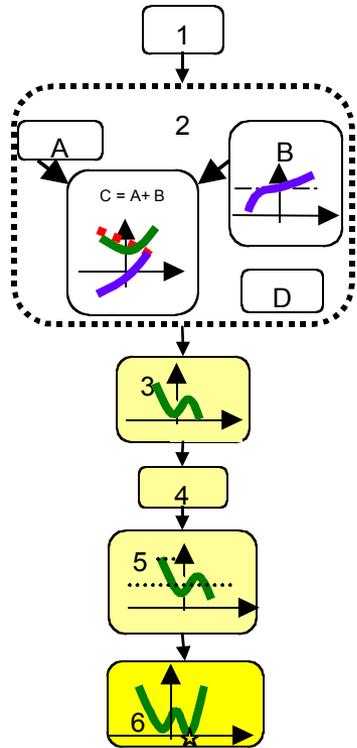
- Electrical Energy, Fuel Energy and Emissions found as they vary with torque distributions



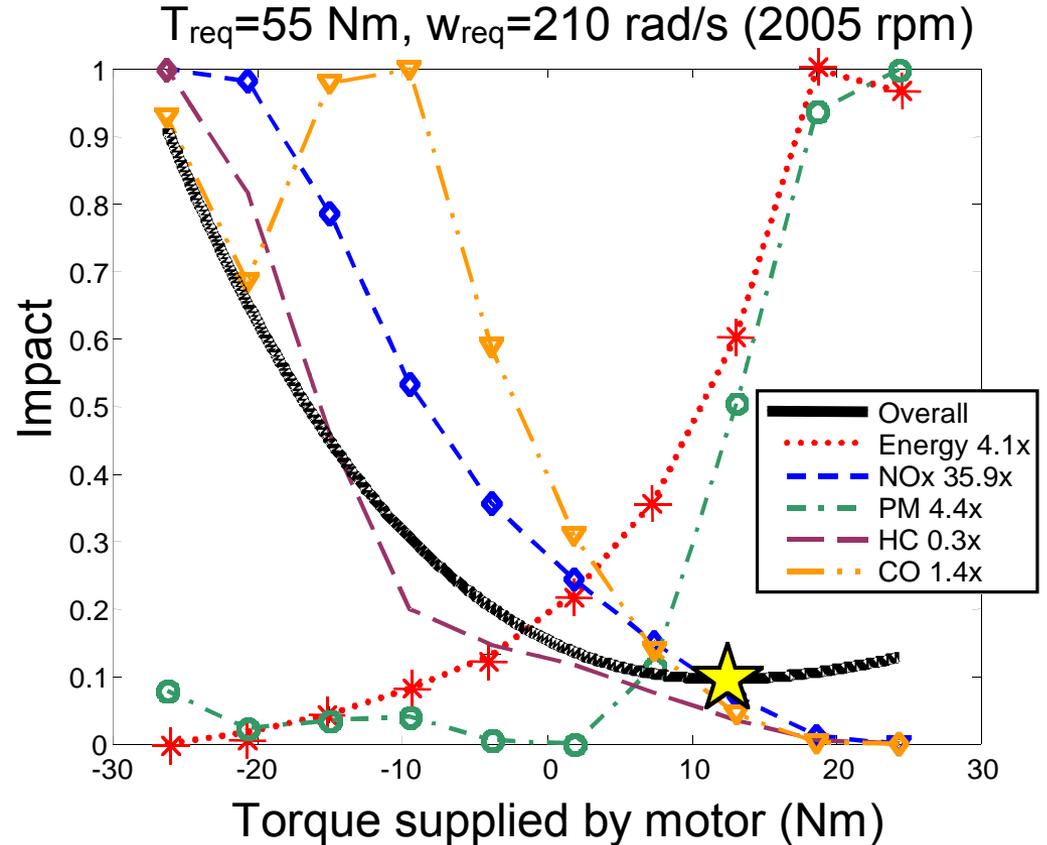


# Impact Function

- 5 competing metrics are combined into a single **Impact Function**



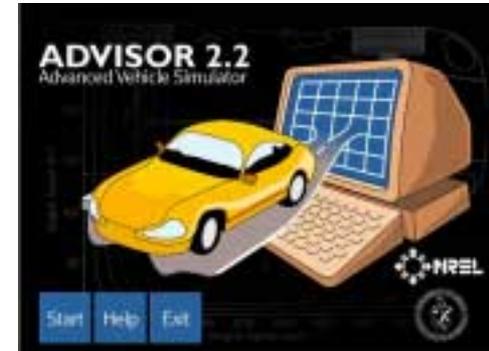
- Normalization
- Target performance weighting
- Minimize





# Simulation Description

- Vehicle Simulated with ADVISOR
- Cycles:
  - FTP
  - HWFET
  - US06
  - J-1015
  - NEDC



<i>Parameter</i>	<i>Value</i>	<i>Details</i>
Engine	42 kW	CIDI, scaled from 67kW VW 1.9L
Motor	32 kW	AC, scaled from Westinghouse 75 kW
Batteries	Twelve 18 Ah	spiral-wound lead acid
Mass	1028 kg	(2266 lbs)
Cd	0.2	
Area	2 m <sup>2</sup>	

- Charge-sustaining



## Simulation, cont.

- RTCS was compared to baseline parallel electric assist
  - Baseline optimized over city-highway
- These ADVISOR runs with RTCS showed a heavy **reliance** of operating point **on NOx** emissions
  - Baseline steady state map from transient tests
  - Diesel engine used
  - Currently have a temperature correction factor of 8X cold-to-hot for NOx emissions
  - Enhanced emissions modeling in ADVISOR is ongoing

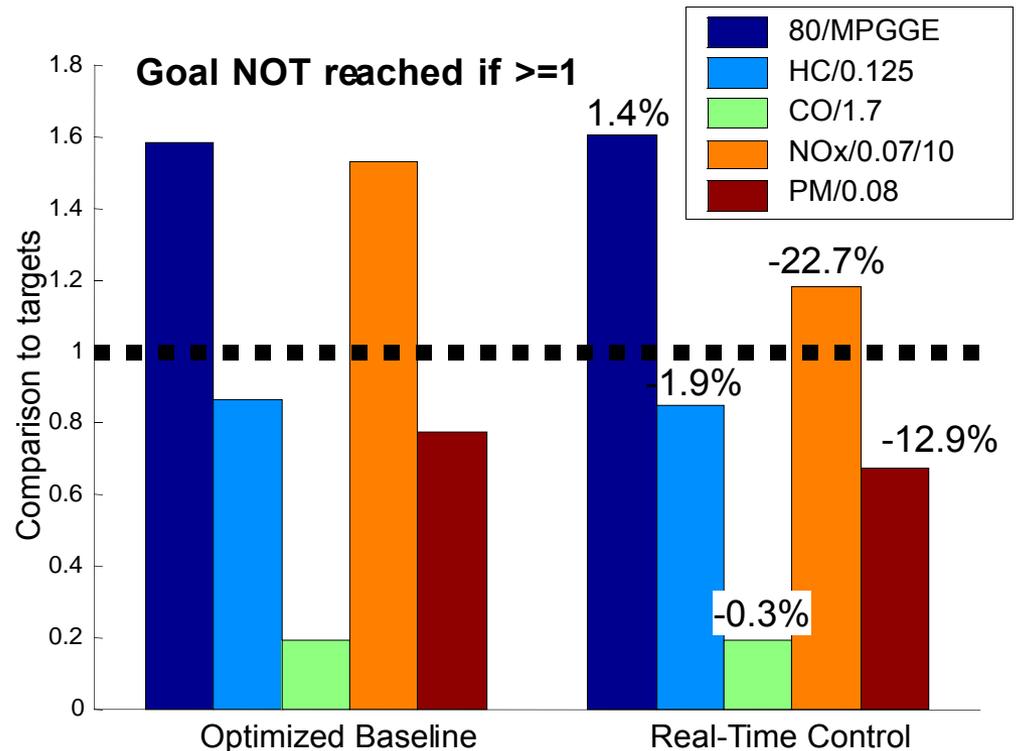




# Results: Optimized Baseline and RTCS vs. Targets

## ■ FTP cycle

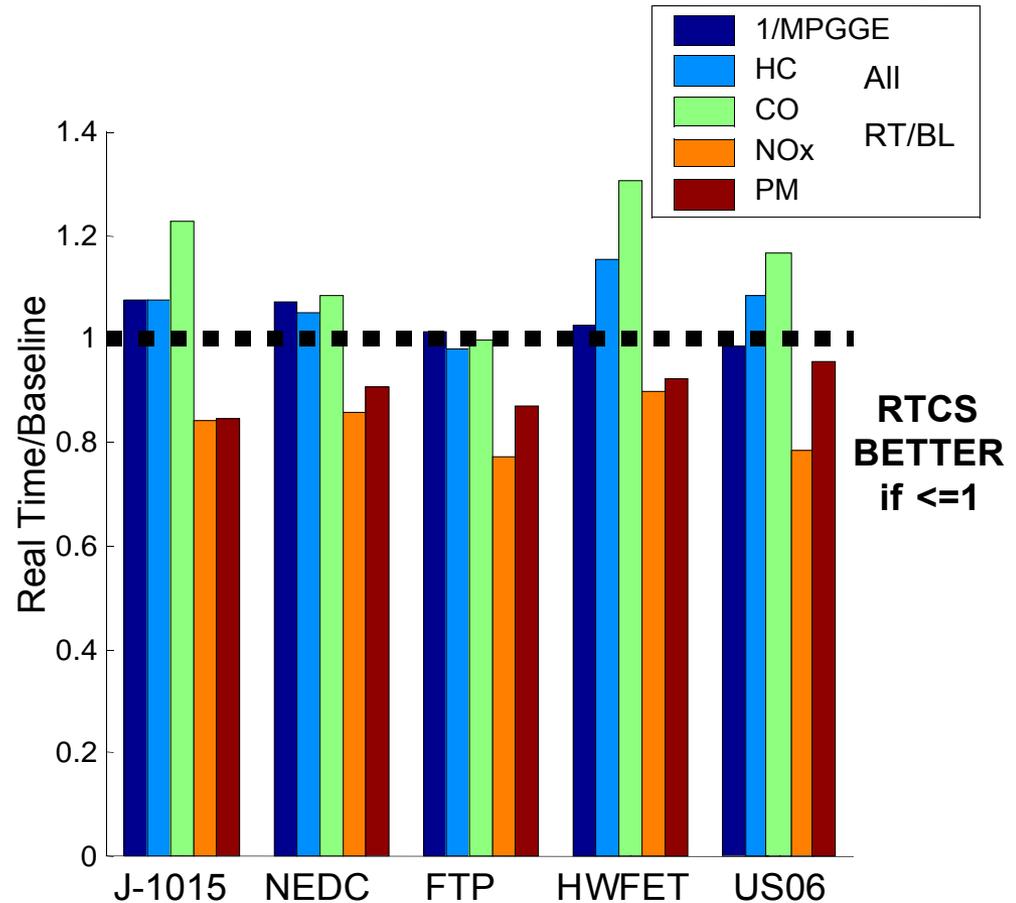
- Energy consumption increased 1.4%
- NOx dropped 22.7%
- PM dropped 12.9%
- HC dropped 1.9%
- CO dropped 0.3%





# Results: Baseline vs. RTCS over multiple cycles

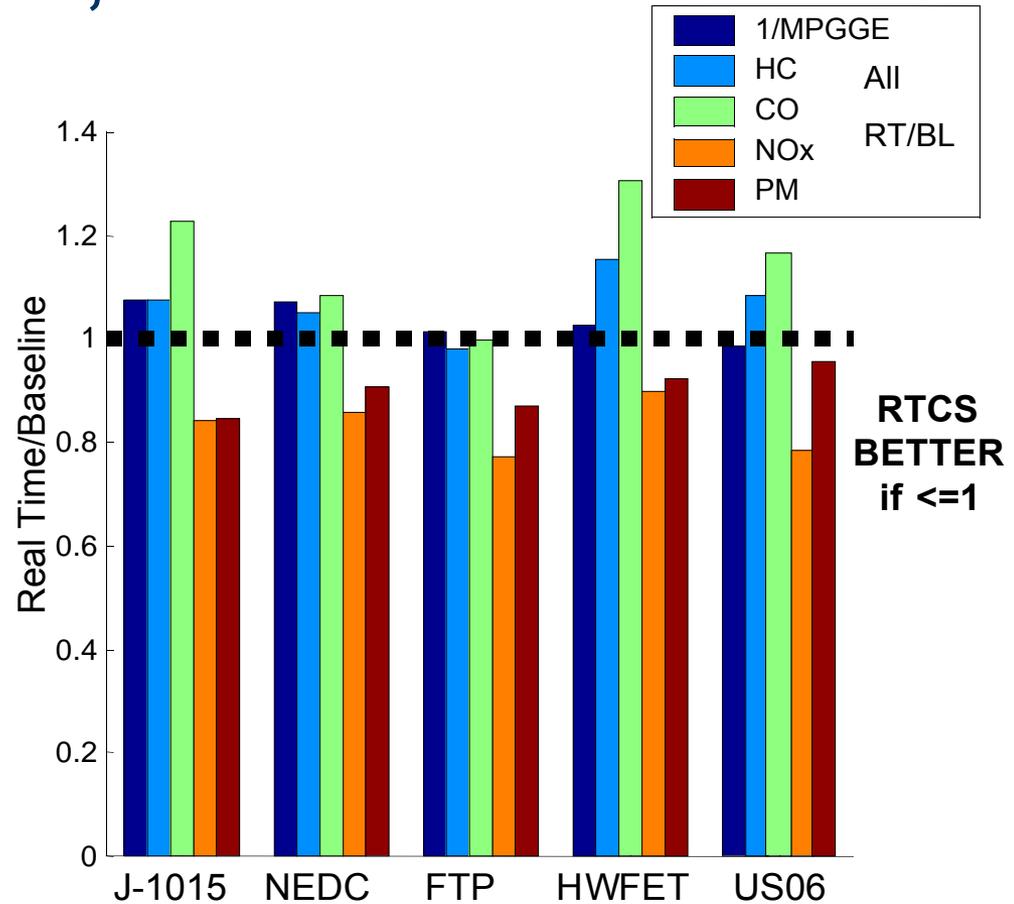
- NOx and PM significantly lower than baseline
  - 17% NOx and 10% PM on average
- Sacrifice of an increase in energy consumption
  - 3.4% average
- HC and CO emissions allowed to increase
  - remained below targets





# Results: Baseline vs. RTCS over multiple cycles, cont.

- Flexibility to adjust to drive cycles
- Optimize on the fly

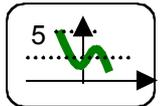
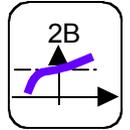




# Summary of RTCS

## ■ RTCS Concepts

- Value of battery charge quantified based on the equivalent amount of fuel to replace that battery energy
- Relative importance of fuel economy and emissions through weightings.
- Overall impact function predicts instantaneous cycle performance (mpg, gpm) and combines five goals into one goal



## ■ RTCS Flexibility

- User-selectable targets
- Real-time adjustment to driving cycles based on expected free regenerative braking energy
- Incorporation of temperature effects on fuel use, engine-out emissions, and catalyst behavior





# Conclusions and Future Work

## ■ RTCS Advantages

- Significant **NOx and PM emissions benefits** over the optimized static control strategy for the FTP cycle (**23%** and **13%** drop) at the price of a slight drop in fuel economy
- Better emissions performance over a range of drive cycles, coupled with comparable energy consumption
- Smaller **variation** in fuel economy over a range of cycles (Baseline: **29%** down to RTCS: **16%**)

## ■ Future Work

- Include RTCS in ADVISOR public release
- Further RTCS development
  - Emissions penalty of battery energy
  - Shifting strategies



# The End

- Paper and ADVISOR at [www.ctts.nrel.gov/analysis](http://www.ctts.nrel.gov/analysis)
- Questions